

Arducam Stereo Camera Adapter Board

User Guide: Set-Up Instructions

SKU: B016601

INTRODUCTION

This multi-camera adapter board is designed for Raspberry pi ZERO and let you connect two 5MP or 8MP cameras to Pi Zero.

Only one of the two cameras can be activated at a time; they are working in alternate ways. It cannot run two cameras at the same time, but we build a simple software which can run two cameras and make it looks working at the same time.

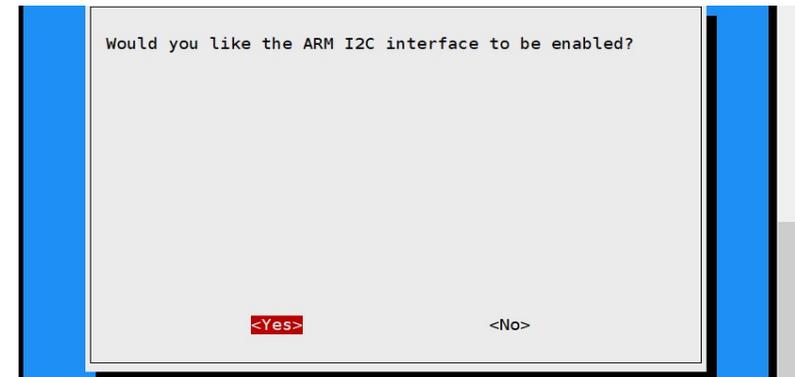
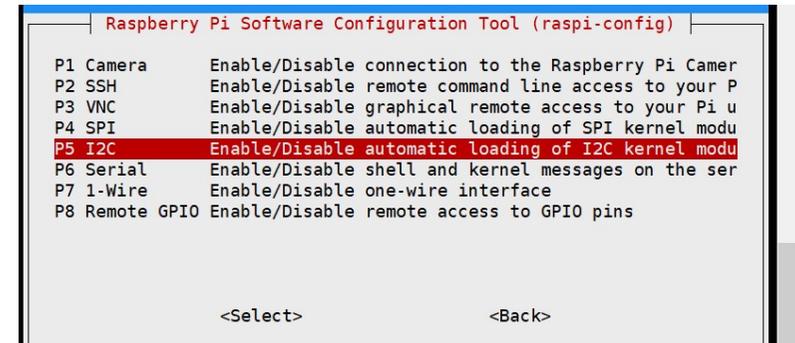
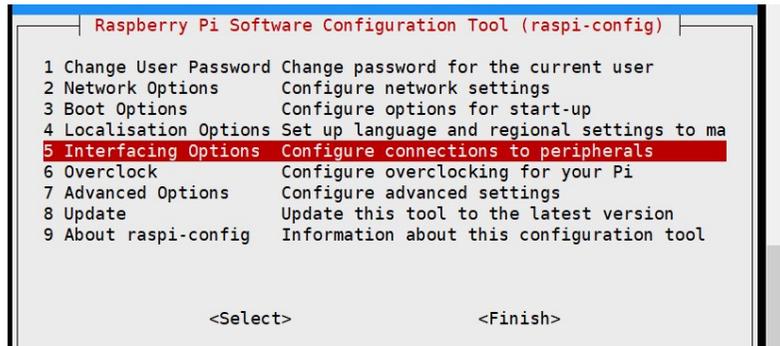
But the drawback is the frame rate, and resolution will be fairly low, may be useful for surveillance.

Please note that Raspberry Pi multi-camera adapter board is a nascent product that may have some stability issues and limitations because of the cable's signal integrity and RPi's closed source video core libraries, so use it on your own risk. This version doesn't support 8MP Pi camera board. And it also can be used for other Raspberry Pi boards with minor software modifications.

PREREQUISITES

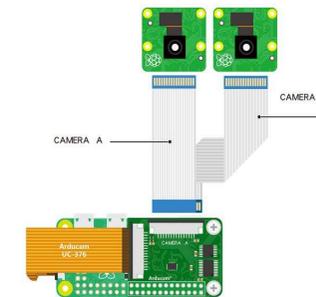
Because the camera switching is done through the camera led pin. You have to disable the automatic management of camera led in `/boot/config.txt`. The following command helps you disable the led control from the GPU firmware.

```
pi@raspberrypi:~ $ sudo raspi-config
```



HARDWARE CONNECTION

Connect the multi-camera adapter board to Pi ZERO through 24 cable pin And connect two 5MP pi cameras to the Camera A and Camera B ports as the following photo shows.



Quick start

■ Download the Raspberrypi library

```
git clone https://github.com/ArduCAM/Raspberrypi.git
```

```
pi@raspberrypi:~ $ git clone https://github.com/ArduCAM/Raspberrypi.git
```

■ Shell version

This shell script demonstrates how to take two still images from two cameras in turn. Each camera will preview for 5 seconds and then take a photo saved to the local file system. Users can directly see the tested pictures.

- Run the script

```
cd RaspberryPi/Multi_Camera_Adapter/Multi_Adapter_Board_2Channel_uc444/shell
sudo chmod +x pi_cam_uc444.sh
sudo ./pi_cam_uc444.sh
```

- Run the demo

```
pi@raspberrypi:~/RaspberryPi/Multi_Camera_Adapter/Multi_Adapter_Board_2Channel/shel
l $ sudo ./pi_cam_uc444.sh
Choose camera A
Choose Camera B
Test OK
```

■ C++ version code

This example demonstrates to run two cameras and make them look at the same

- Install the opencv library

```
sudo apt-get install libopencv-dev
```

- Compile and run

```
cd RaspberryPi/Multi_Camera_Adapter/Multi_Adapter_Board_2Channel_uc444
sudo make
sudo ./arducam_multi_adapter_uc444
```

- Run the demo

